

Appl. No. 10/605,778  
Response dated 3/15/2005  
Reply to Office Action of 9/15/2004

### AMENDMENTS TO CLAIMS

This listing of claims will replace all prior versions, and listings, of claims in the application:

#### Listing of Claims

1. (currently amended) A system comprising:  
a platform coupled with sheaves that do not comprise brakes;  
a YZ movement rope configured to move said platform; and,  
a Z movement device configured to move said YZ movement rope-rope;  
a Y movement motor coupled with said YZ movement rope;  
a Z movement motor coupled with said Z movement device; and,  
a computer coupled with said Y movement motor and said Z movement motor and configured to  
control said YZ movement rope in a Y axis and a Z axis.
2. (canceled)
3. (canceled)
4. (canceled)
5. (canceled)
6. (canceled)
7. (canceled)
8. (canceled)
9. (canceled)
10. (canceled)
11. (canceled)
12. (canceled)
13. (original) The system of claim 1 further comprising at least two support structures.

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14. (currently amended) A method comprising:

coupling a YZ movement rope to ~~said platform~~ a platform via sheaves that do not comprise brakes; and,

coupling a Z movement device to said YZ movement ~~rope~~ rope;

coupling said YZ movement rope to a Y movement motor;

coupling said Z movement device to a Z movement motor;

coupling a computer with said Y movement motor and said Z movement motor; and,

controlling said YZ movement rope in a Y axis and a Z axis with said computer by rotating said Y movement motor and rotating said Z movement motor in order to move said platform.

15. (canceled)

16. (canceled)

17. (currently amended) A system comprising:

means for coupling a YZ movement rope to ~~said platform; and,~~ a platform via sheaves that do not comprise brakes;

means for coupling a Z movement device to said YZ movement ~~rope~~ rope;

means for coupling said YZ movement rope to a Y movement motor;

means for coupling said Z movement device to a Z movement motor;

means for coupling a computer with said Y movement motor and said Z movement motor; and,

means for controlling said YZ movement rope in a Y axis and a Z axis with said computer coupled to rotate said Y movement motor and rotate said Z movement motor in order to move said platform.

18. (canceled)

19. (canceled)

20. (canceled)